

ABSTRACT

The performance of a system for controlling vehicle-
movement dynamics, which operates by means of the braking
5 system and the drive train of a vehicle in order to prevent
lateral breakaway of the vehicle, is improved yet further
for the case in which oversteering of the vehicle is to be
compensated. To this end it is proposed, according to the
invention, that a braking moment be produced, by means of
10 the braking system, on the front wheel on the outside of
the bend, and an additional drive moment be built up, by
means of the drive train, on the driven wheels.